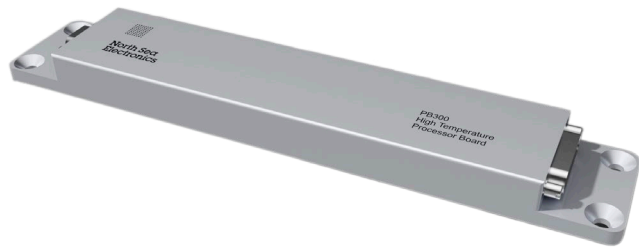




Features

- Highly versatile processor board for downhole or other demanding applications
- 2 x Analog differential inputs with programmable gain
- CAN and RS485 interface
- 2 x Open Drain outputs
- 2Mbit HT FRAM
- 64Mbit HT Flash Memory (Optional)
- 3 axis accelerometer
- 18-32Vdc Input voltage range
- CNC Machined aluminum housing



Product Description

The NSE HT PB300 is a highly flexible, high temperature processor board. It is targeted at downhole wireline and drilling tools or other industrial applications where high temperature and severe shock and vibration may occur.

The NSE HT PB300 enables the user rapidly to progress the development of “smart tools” and cut cost by allowing the user to focus on algorithms and tool design. The board features the most common input and output (I/O) requirements and interfaces, such as analog bridge inputs (x2), open drain outputs (x2) for solenoid or relay switching, communication (CANbus and RS485) and several I/O pins. In addition, it has an onboard temperature sensor, accelerometer and a flash memory that gives the board a high level of flexibility.

The user can choose to develop its own firmware for the controller, or he can take advantage the extensive in-house experience in firmware development at NSE. If a customer chooses to write its own algorithms/firmware, NSE will provide drivers for all of the board’s hardware.

The NSE HT PB300 PCB layout is made with ruggedness in mind. A CNC machined aluminum chassis provides maximum mechanical support to allow the board to operate in a very high shock and vibration environment. The board uses high temperature specified, military type “micro D” connectors.

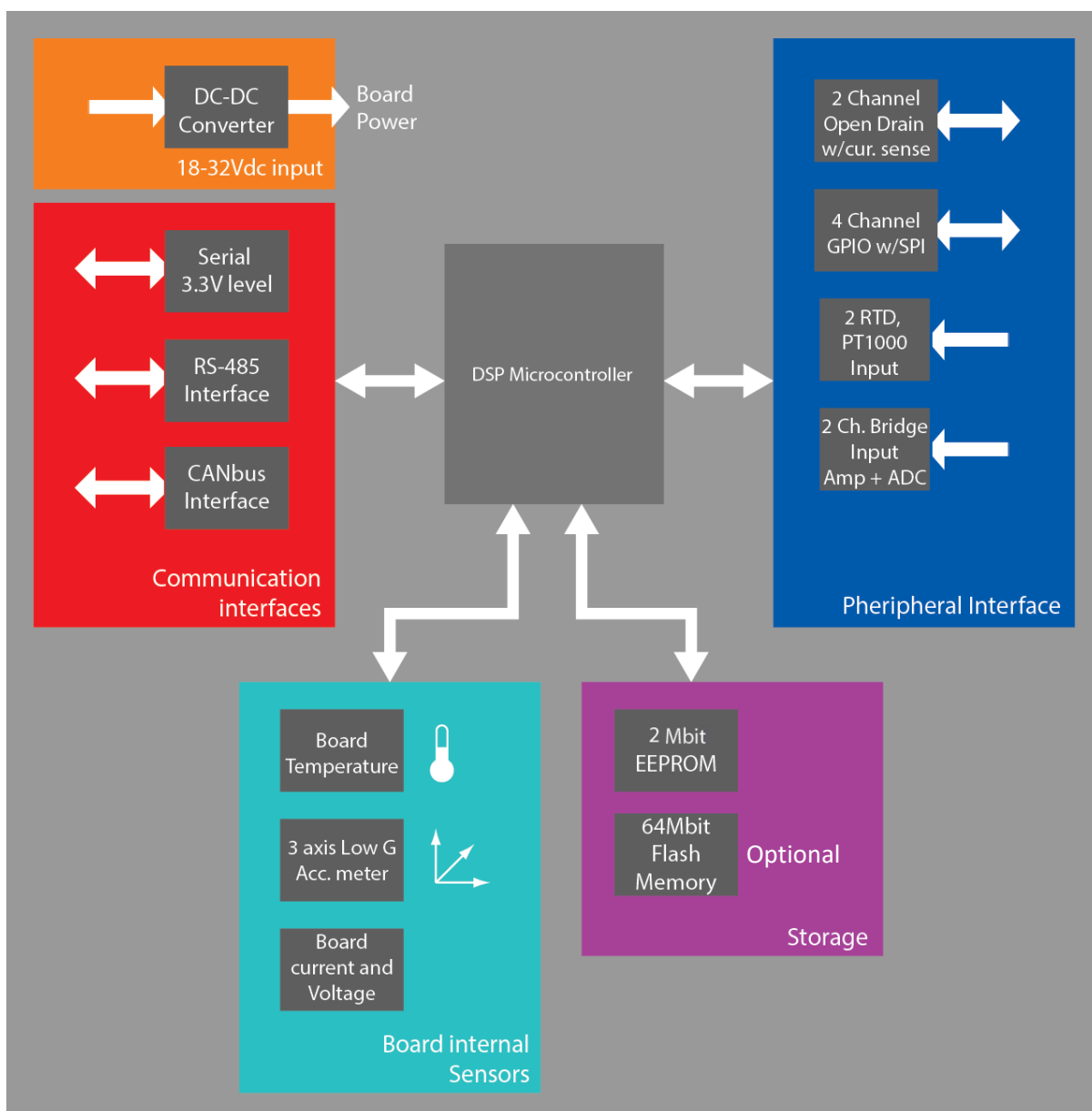
1 Board Overview

The NSE HT PB300 Processor Board features a DSP Microcontroller paired with an accurate high temperature oscillator. This is a proven solution from NSE and has been tested and verified in several designs that are in operation worldwide.

All peripherals are connected to the controller through dedicated IO pins, communication buses or SPI.

The combination of a proven design layout, good support, extensive documentation, and base driver firmware for all IO functions allow for rapid development of applications and algorithms.

1.1 Board block diagram



2 Board Specifications

| | Min | Typ | Max | Unit |
|----------------------------------|-----|-----|-----|--------------------------------|
| Physical size | | | | |
| Length PCB | | 167 | | mm (including connectors) |
| Width PCB | | 34 | | mm |
| Length chassis | | 200 | | mm |
| Width chassis | | 37 | | mm |
| Height chassis | | 14 | | mm |
| Environmental | | | | |
| Operating Temperature | 0 | | 177 | Deg C |
| Storage Temperature | -40 | | 60 | Deg C |
| Power | | | | |
| Voltage supply | 18 | 28 | 32 | Vdc |
| Supply Input Current | | 20 | | mA@28V |
| Integrated sensors | | | | |
| Onboard temperature sensor range | 0 | | 190 | Deg C |
| Temperature sensor error | | | ±3 | Deg C |
| Input voltage measurement range | 15 | | 36 | Volt |
| Input voltage measurement error | | | ± 3 | % |
| Input Current measurement range | 0 | | 50 | mA – excluding solenoid output |
| Input Current measurement error | | | ± 5 | % of full scale output |
| On board logic voltage | | 3.3 | | Volt |
| Logic voltage measurement error | | | ± 3 | % |
| Bridge excitation voltage | | 2.5 | | Volt |
| Bridge voltage measurement error | | | ± 3 | % |
| Accelerometer axis | | 3 | | X,Y,Z (optional) |
| Accelerometer range | -2 | | 2 | g (optional) |
| Accelerometer measurement error | | | | To be determined |
| Accelerometer temperature range | 0 | | 150 | degC |
| Onboard Memory | | | | |
| Flash (Optional) | | 64 | | Mbit |
| EEPROM | | 2 | | Mbit |
| Analog input | | | | |
| RTD channels | | 2 | | 2-Wire PT1000 |
| RTD Temperature range | 0 | | 360 | Deg C |
| Wheatstone bridge input channels | | 2 | | Differential input |
| Bridge input gain | 1 | | 128 | |
| Bridge resistance | 100 | | | Ohms |
| Bridge excitation voltage | | 2.5 | | Volts |
| ADC resolution | | | 24 | Bits |
| Sampling rate | | | 7 | Samples per sec |

| | | |
|--------------------------------|---------------------|-----------------------------|
| GPIO (TTL) | | |
| GPIO pins | 4 | 3.3V Logic |
| Onboard pull-up resistor value | 100k | ohm |
| High voltage level input | 2.6 | Volt |
| Low voltage level input | | 0.7 |
| SPI bus pins | 3 | 3.3V Logic |
| SPI bus speed | 250 | kb/s clock frequency |
| Solenoid Output | | |
| Channels | 2 | |
| Solenoid Output voltage | Board Input Voltage | |
| Current rating | 0.5 | A |
| Current measurement error | ± 5 | % of full scale output |
| Communication | | |
| CAN bus channels | 1 | |
| CAN bus default baud rate | 250 | kbps |
| RS485 channels | 1 | |
| Serial TTL channels | 1 | |
| Connectors | | |
| H2 | M83513/13-B type | COM / Power (15-socket R/A) |
| H1 | M83513/10-E type | Peripherals (31-pin R/A) |

2.1 Thermal properties

The NSE High Temperature PB300 is designed to operate in a 177°C environment.

In a typical assembly, the **NSE UNIT** is mounted to a **MOUNTING PROFILE** that is located inside an **OUTER HOUSING**.

The **OUTER HOUSING** surface temperature should not rise above the specified maximum ambient temperature, and the mechanical design and interface between the **OUTER HOUSING, MOUNTING PROFILE** and the **NSE UNIT** should be such that the thermal resistance specification is achieved.



2.2 Connectors

2.2.1 H2 communication and power

PB300 Connector: Micro D - M83513/13-B type High Temperature - 15 pin connector.

Mating connector: T.B.D

| Pin | Signal name | Description / Function |
|-----|--------------|---------------------------------|
| 1 | +VIN | Supply voltage input |
| 2 | +VIN | Supply voltage input |
| 3 | GND | Ground |
| 4 | GND | Ground |
| 5 | GND | Ground |
| 6 | GND | Ground |
| 7 | TTL_TX | Serial TTL TX |
| 8 | TTL_RX | Serial TTL RX |
| 9 | GND | Ground |
| 10 | CANH | CAN High - CAN bus |
| 11 | CANL | CAN Low - CAN bus |
| 12 | CAN Shield | GROUND through 1206 0Ω resistor |
| 13 | RS485A | RS485A |
| 14 | RS485B | RS485B |
| 15 | RS485 Shield | GROUND through 1206 0Ω resistor |

2.3 H1 - Peripherals

Connector H1 will be a M83513/10-E type 31-pin pin contacts right angle connector. Signals on connector H1 are grouped on the connector for improved noise behavior.

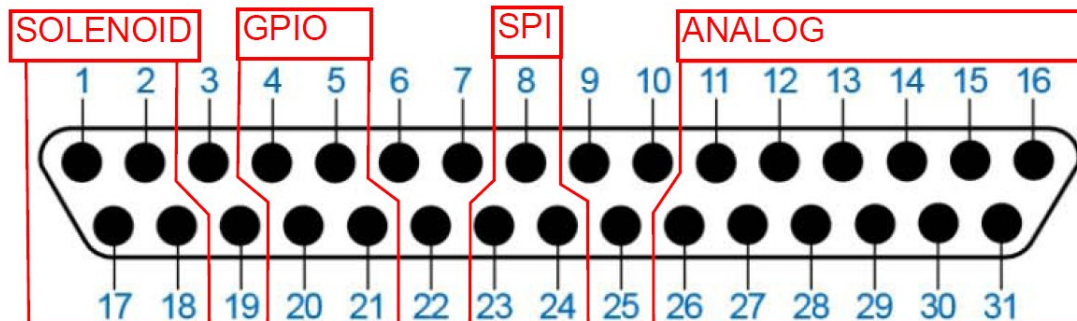
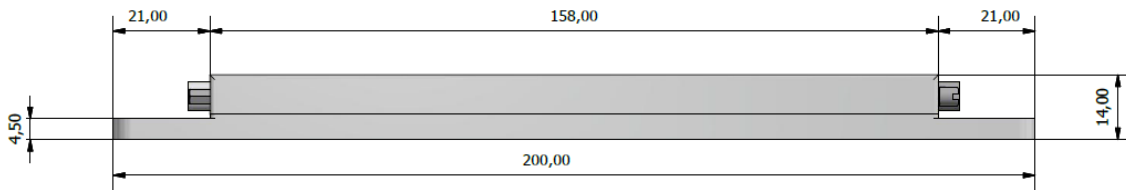


Figure 1 - Connector H2 signal placement

| Pin Number | Signal name | Description |
|------------|-------------|----------------------------------|
| 1 | Solenoid 1+ | Solenoid 1 Supply |
| 2 | Solenoid 1- | Solenoid 1 Return |
| 3 | GND | GROUND |
| 4 | GPIO1 | General Purpose I/O CH1 |
| 5 | GPIO2 | General Purpose I/O CH2 |
| 6 | GND | GROUND |
| 7 | GND | GROUND |
| 8 | SCK | Optional SPI clock |
| 9 | GND | GROUND |
| 10 | GND | GROUND |
| 11 | GND | GROUND |
| 12 | GND | GROUND |
| 13 | RTD1+ | RTD channel 1+ |
| 14 | RTD1- | RTD channel 1- |
| 15 | RTD2+ | RTD channel 2+ |
| 16 | RTD2- | RTD channel 2- |
| 17 | Solenoid 2+ | Solenoid 2 Supply |
| 18 | Solenoid 2- | Solenoid 2 Return |
| 19 | GND | GROUND |
| 20 | GPIO3 | General Purpose I/O CH3 |
| 21 | GPIO4 | General Purpose I/O CH4 |
| 22 | +3V3 | +3V3 logic voltage |
| 23 | MOSI | Optional SPI Master Output |
| 24 | MISO | Optional SPI Master Input |
| 25 | GND | GROUND |
| 26 | +2.5V | Bridge Excitation Voltage – 2.5V |
| 27 | +2.5V | Bridge Excitation Voltage – 2.5V |
| 28 | Bridge1+ | Differential Input Channel 1+ |
| 29 | Bridge1- | Differential Input Channel 1- |
| 30 | Bridge2+ | Differential Input Channel 2+ |
| 31 | Bridge2- | Differential Input Channel 2- |

3 Mechanical Dimensions



Consult NSE for 3D step model of chassis.

4 Datasheet Revision History

| REV | DATE | DESCRIPTION | PREP | APPR |
|-----|------------|-------------------------------|------|------|
| A | 05.09.2017 | Initial Revision | RFY | GLK |
| B | 04.06.2018 | Updated | RFY | GLK |
| C | 24.02.2021 | Updated with new memory sizes | RFY | |

5 Ordering

5.1 Order code

| | | | | | |
|-----------------|----------|---|-----------------|------------|-----------|
| | | Order code: | NSE-5003 | -03 | -B |
| Category | NSE-5003 | = NSE HT Processor Boards | | | |
| Model | -03 | = PB300 Processor Board | | | |
| Variant | -A | = 2Mbit EEPROM (FRAM) Memory (Standard) | | | |
| | -C | = 64k-bit SPI Serial HT EEPROM (Optional) | | | |
| | -D | = 2Mbit FRAM and 64Mbit Flash Memory (Optional) | | | |

5.2 Where to buy

Email: sales@nse.no
 Web: www.nse.no
 Phone: +47 406 48 400

